

Model Documentation of the Buck-Boost Converter

1 Nomenclature

1.1 Nomenclature for Model Equations

| | |
|-------|------------------------------|
| L | inductivity of the inductor |
| C | capacity of the capacitor |
| R | resistance of the load |
| U_E | input voltage |
| i_L | current through the inductor |
| u_C | voltage over the capacitor |
| d | duty ratio of the switch |

1.2 Circuit Diagram

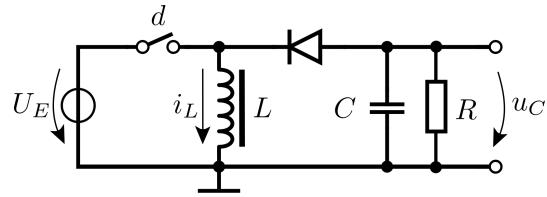


Figure 1: Circuit

2 Model Equations

State Vector and Input Vector:

$$\underline{x} = (x_1 \ x_2)^T = (i_L \ u_C)^T$$

$$\underline{u} = d$$

System Equations:

$$\dot{x}_1 = (1 - u) \frac{1}{L} x_2 + \frac{U_E}{L} u \quad (1a)$$

$$\dot{x}_2 = -(1 - u) \frac{1}{C} x_1 - \frac{1}{RC} x_2 \quad (1b)$$

Parameters: L, C, R, U_E

Outputs: $x_2 = u_C$

2.1 Exemplary parameter values

| | | Symbol | Value |
|---------------|-------|---------------------|----------|
| Inductiviy | L | 0.00018 | H |
| Capacity | C | $2.0 \cdot 10^{-5}$ | F |
| Resistance | R | 10 | Ω |
| Input Voltage | U_E | 24 | V |

3 Derivation and Explanation

See boost converter.

4 Simulation

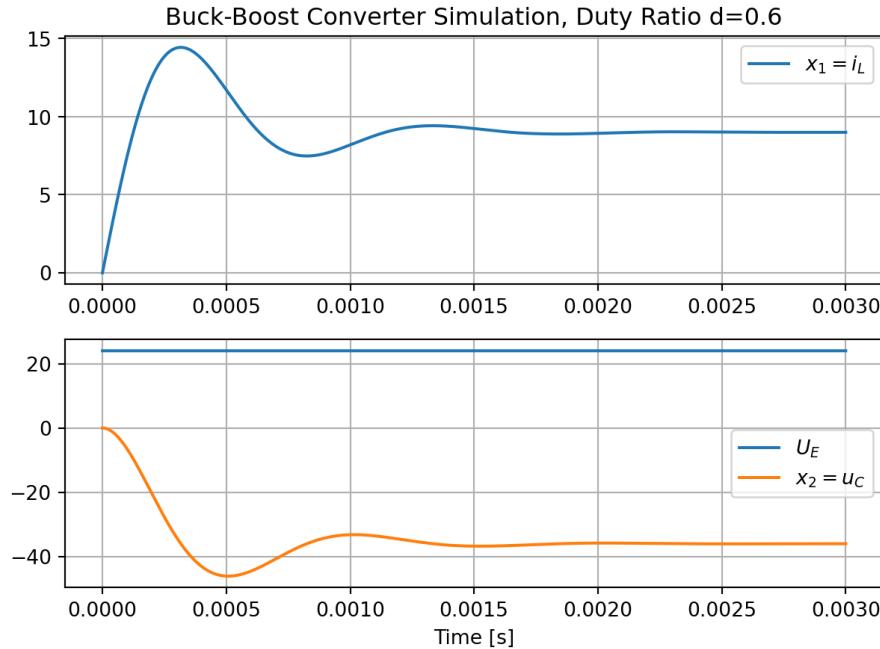


Figure 2: Simulation of the buck-boost converter.

References

- [1] R. H. G. Tan and L. Y. H. Hoo, DC-DC converter modeling and simulation using state space approach, in 2015 IEEE Conference on Energy Conversion (CENCON), Oct. 2015, pp. 42–47. doi: 10.1109/CENCON.2015.7409511.
- [2] K. Röbenack, Nichtlineare Regelungssysteme: Theorie und Anwendung der exakten Linearisierung. Berlin, Heidelberg: Springer Berlin Heidelberg, 2017. doi: 10.1007/978-3-662-44091-9.