

Model Documentation of the 'L-1011 aircraft in cruise flight conditions'

1 Nomenclature

1.1 Nomenclature for Model Equations

- x state vector
- u control input vector
- w noise vector
- z regulated output vector
- y measurement vector

2 Model Equations

State Vector and Input Vector:

$$x \in \mathbb{R}^5 \quad u \in \mathbb{R}^2 \quad w \in \mathbb{R}^5 \quad z \in \mathbb{R}^5 \quad y \in \mathbb{R}^4$$

System Equations:

$$\dot{x}(t) = Ax(t) + B_1w(t) + Bu(t) \tag{1a}$$

$$z(t) = C_1x(t) + D_{11}w(t) + D_{12}u(t) \tag{1b}$$

$$y(t) = Cx(t) + D_{21}w(t) \tag{1c}$$

Outputs: z

2.1 Exemplary parameter values

| Symbol | Value |
|----------|---|
| A | $\begin{bmatrix} 0 & 0 & 1.0 & 0 & 0 \\ 0 & -0.154 & -0.0042 & 1.54 & 0 \\ 0 & 0.249 & -1.0 & -5.2 & 0 \\ 0.0386 & -0.996 & -0.0003 & -0.117 & 0 \\ 0 & 0.5 & 0 & 0 & -0.5 \end{bmatrix}$ |
| B | $\begin{bmatrix} 0 & 0 \\ -0.744 & -0.032 \\ 0.337 & -1.12 \\ 0.02 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$ |
| B_1 | $\begin{bmatrix} -0.744 & -0.032 \\ 0.337 & -1.12 \\ 0.02 & 0 \\ 0 & 0 \end{bmatrix}$ |
| C_1 | $\begin{bmatrix} 1.0 & 0 & 0 & 0 & 0 \\ 0 & 1.0 & 0 & 0 & 0 \\ 0 & 0 & 1.0 & 0 & 0 \\ 0 & 0 & 0 & 1.0 & 0 \\ 0 & 0 & 0 & 0 & 1.0 \end{bmatrix}$ |
| C | $\begin{bmatrix} 0 & 1.0 & 0 & 0 & -1.0 \\ 0 & 0 & 1.0 & 0 & 0 \\ 0 & 0 & 0 & 1.0 & 0 \\ 1.0 & 0 & 0 & 0 & 0 \end{bmatrix}$ |
| D_{11} | $\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ |
| D_{12} | $\begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 1.0 & 0 \\ 0 & 1.0 \end{bmatrix}$ |
| D_{21} | $\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ |

3 Derivation and Explanation

This model is part of the "COMpleib" - library and was automatically imported into ACKREP.

The original description was:

AC3 L-1011 aircraft in cruise flight conditions C. Edwards and S. K. Spurgeon, "On the development of discontinuous observers", IJOC, Vol. 59, Nr. 5, pp. 1211-1229, 1994

4 Simulation

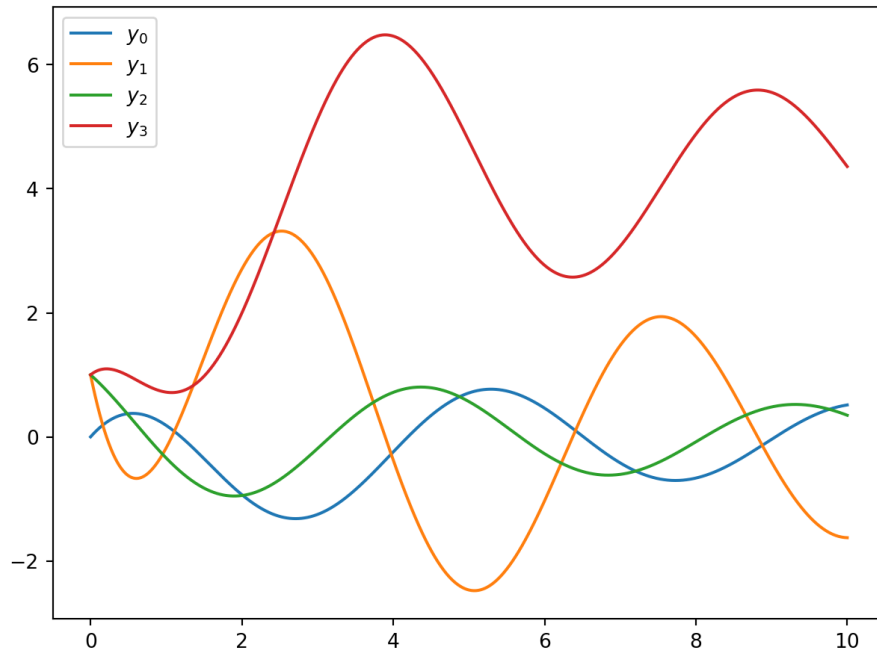


Figure 1: Simulation of the L-1011 aircraft in cruise flight conditions.

References

- [1] . Edwards and S. K. Spurgeon, "On the development of discontinuous observers", IJOC, Vol. 59, Nr. 5, pp. 1211-1229, 1994