Model Documentation of the '2-degree-of-freedom 2DOF tuned-mass damper TMD'

1 Nomenclature

1.1 Nomenclature for Model Equations

- x state vector
- u control input vector
- w noise vector
- z regulated output vector
- y measurement vector

2 Model Equations

State Vector and Input Vector:

$$x \in \mathbb{R}^6 u \qquad \qquad \in \mathbb{R}^2 w \in \mathbb{R}^1 z \qquad \qquad \in \mathbb{R}^3 y \in \mathbb{R}^4$$

System Equations:

$$\dot{x}(t) = Ax(t) + B_1w(t) + Bu(t)$$
(1a)
$$x(t) = C_1x(t) + D_2x(t) + D_12x(t)$$
(1b)

$$z(t) = C_1 x(t) + D_{11} w(t) + D_{12} u(t)$$
(1b)

$$y(t) = Cx(t) + D21w(t)$$
(1c)

Outputs: z

Symbol	Value
Symbol	
A	
В	0 0
	0 0
	0 0
	-1.625 0.625
	0.625 - 1.625
	0.2 0.2
B_1	
	0 0
	0 0
	-1.625 0.625
	0.625 - 1.625
	0.2 0.2
C_1	
C	
	$\begin{bmatrix} 0 & 0 & 0 & 1.0 & 0 & 1.0 \\ 0 & 1.0 & -1.0 & 0 & 0 & 0 \end{bmatrix}$
D ₁₁ D ₁₂	
	0
	0
D_{21}	-0.01
ν_{21}	

2.1Exemplary parameter values

3 **Derivation and Explanation**

This model is part of the "'COMPleib"' - library and wasautomatically imported into ACKREP.

The original description was:

TMD 2-degree-of-freedom 2DOF tuned-mass damper TMD L. Zuo and S. A. Nayfeh, "The Multi-Degree-of-Freedom Tuned- Mass-Damper for Suppression of Single-Mode Vibration Under Random and Harmonic Excitation", Dept. of Mech. Engineering, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139, Draft for 2003 ASME Design Engineering Technical Conferences",

4 Simulation



Figure 1: Simulation of the 2-degree-of-freedom 2DOF tuned-mass damper TMD.

References

 Zuo and S. A. Nayfeh, "The Multi-Degree-of-Freedom Tuned- Mass-Damper for Suppression of Single-Mode Vibration Under Random and Harmonic Excitation", Dept. of Mech. Engineering, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139, Draft for 2003 ASME Design Engineering Technical Conferences",